

# LMF SDK v1.9.0.2507 beta What's new?

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## Differences between provided LMF 1.9 beta versions

#### LMF 1.9.0.2507 to 1.9.0.2135

In contrast to LMF 1.9.0.2135, LMF 1.9.0.2507 contains the following major changes

- The latest version contains a fix regarding the disconnection behaviour for the AT960 tracker in combination with the AS1 (see chapter Improvements for the AT9x0 interface).
- The following LMF classes, which were part of previous LMF 1.9 beta versions, are removed:
  - WrtlRemoteBox
  - Internals Namespaces
  - Adapters Namespaces
  - Test.MeasurementResults
- Integration of the RemoteControlTrigger for AT500 (Same as AT40x)
- Bug Fixes

#### LMF 1.9.0.2135 to 1.9.0.1891

In contrast to LMF 1.9.0.1891, LMF 1.9.0.2135 contains the following major implementations

- The B-Probe <sup>plus</sup> will not generate measurements when the user releases the button on the device. Instead, the user receives a button event if the measurement button on the B-Probe plus is pressed manually. By means of the button down event the 3<sup>rd</sup> party software can react correspondingly, e.g. by invoking a measurement with *startMeasurement* (see chapter Support for the new B-Probe<sup>plus</sup>).
- The B-Probe <sup>plus</sup> does not allow and support continuous time or continuous distance measurements. The same restrictions as for the B-Probe regarding the measurement modes also apply for the B-Probe plus (see chapter Support for the new B-Probe<sup>plus</sup>).





## Prerequisites and Compatibility

LMF 1.9 supports the following AT systems and respective system software versions

- Leica Absolute Tracker AT500 v1.0
- Leica Absolute Tracker ATS600 v1.1
- Leica Absolute Tracker AT9x0 v2.2
- Leica Absolute Tracker AT40x v2.4
- Leica Absolute Tracker AT901 v3.8
  - Please note that LMF 1.9 will be the last version to be compatible with the AT901

Most of the new features are due to the introduction of the new Absolute Tracker AT500 and the new B-Probe plus.

LMF 1.9 has the following system requirements:

- Windows 10 or higher
- .Net Framework 4.5
- Visual Studio Redist 2019



## Support for the new Absolute Tracker AT500

The AT500 is a new tracker model comparable to an AT40x. It supports 3d measurements to a reflector, as well as measurements to a simple 6dof device. The differences between an AT500 and an AT40x are explained in more details in the following sections.

#### AT500 available in Simulator

The AT500 Simulator can accessed by using TrackerScope.

<sup>35</sup> TrackerScope			-	· 🗆 🗙
	Trac	kerSco	be	
				٠
Insert IP Address	Custom ConnectBox	192.168.0.1	127.0.0.1:22480	
AT930 Simulator	AT960-LR Simulator	AT901-LR Simulator	AT401 Simulator	
AT402 Simulator	AT403 Simulator	ATS600 Simulator	AT500 Simulator	
ConnectBox Simulate				
TS TrackerScope				- 🗆 ×
-	at	t500simulator		— 🚺
at500simulator	LMF.Tracker.AT500	Tracker		
🔏 Comment	Simulator			
🔏 ExpectedFirmware	1.0.0.0			
A InstalledFirmware	1.0.0.0			
A IPAddress	at500simulator			
🔏 IsCompatibleWithInstalledFirmwar	e 🗹			
🔏 Name	AT500 71005555			
🔏 ProductName	AT500			
🔏 SerialNumber	71005555			



#### Sample Code for connections to the AT500

Additionally, LMF Tracker SDK Setup will install a sample project written in C# showing how to connect to and use the AT500.

Name	Date modified	Туре	Size	
COMSampleProject	26/11/2021 17:02	File folder		
CSharpConnectBoxSampleProject	26/11/2021 17:02	File folder		
CSharpSampleProject	26/11/2021 17:02	File folder		
📕 LabViewSampleProject	26/11/2021 17:02	File folder		
ManagedWrapperSampleProject	26/11/2021 17:02	File folder		
MFCSampleProject	26/11/2021 17:02	File folder		
PythonSampleProject	26/11/2021 17:02	File folder		
VBASampleProject	26/11/2021 17:02	File folder		
VC++ Redistributables	26/11/2021 17:02	File folder		
🧟 Appendix ExternalTriggerInterface.pdf	26/11/2021 00:08	Foxit PDF Reader	839 KB	
💁 deploy32Bit.bat	26/11/2021 00:08	Windows Batch File	1 KB	
🖭 deploy64Bit.bat	26/11/2021 00:08	Windows Batch File	1 KB	
🧟 LMF Tracker User Guide.pdf	26/11/2021 15:09	Foxit PDF Reader	2,241 KB	
LMF.Tracker.Connection.dll	26/11/2021 15:07	Application extens	16,390 KB	
LMF.Tracker.Connection.tlb	26/11/2021 17:02	TLB File	382 KB	
LMF.Tracker.Connection.xml	26/11/2021 15:06	XML Document	439 KB	
LMFDocumentation.chm	26/11/2021 15:13	Compiled HTML H	5,278 KB	
Logalyzer.exe	26/11/2021 14:52	Application	5,110 KB	
TrackerScope.exe	26/11/2021 15:10	Application	9,257 KB	
🖭 undeploy32Bit.bat	26/11/2021 00:08	Windows Batch File	1 KB	
🖭 undeploy64Bit.bat	26/11/2021 00:08	Windows Batch File	1 KB	
unins000.dat	26/11/2021 17:02	DAT File	588 KB	
🞼 unins000.exe	26/11/2021 17:02	Application	1,175 KB	

The simulator is started by pressing on the corresponding tracker type.



Sharp Sample Project				-		
nect Main Profiles Positioning Probe Triggers OVC /	Scanning Alignment TrackerErro	ors				
IP:					Connect	
Connect to Simulator						
,	AT500 ATS600 A	T401 AT402	AT403 AT901	AT930	AT960-LF	2
Discover Trackers						
					Discover	<b>r</b>
				,	Disconn	iect
Sharp Sample Project ect Main Profiles Positioning Probe Triggers OVC / Scar	nning Alignment TrackerErrors			- [	- ×	
Sharp Sample Project ect Main Profiles Positioning Probe Triggers OVC / Scar Commands	nning Alignment TrackerEirors			- [		
Sharp Sample Project ect Main Profiles Positioning Probe Triggers OVC / Scar Commands Initialize Preconditions	nning Alignment TrackerErrors	0.1806		- [	- ×	
Sharp Sample Project ect Main Profiles Positioning Probe Triggers OVC / Scar Commands Initialize Preconditions Measure	nning Algnment TrackerEmors	0.1806	AT500 7	- [	- ×	
Sharp Sample Project ect Main Profiles Positioning Probe Triggers OVC / Scar Commands Initialize Preconditions Measure Start Measurement Stop Measurement	nning Algnment TrackerEnors	0.1806	AT500 7 at500si	[ 1005555 mulator	- ×	
Sharp Sample Project ect Main Profiles Positioning Probe Triggers OVC / Scar Commands Initialize Preconditions Measure Start Measurement Stop Measurement DBO Smam	nning Algoment TrackerEirors	0.1806 n Active StayOnTop	AT500 7 at500sin	— [ 1005555 nulator	- ×	
Sharp Sample Project ect Main Profiles Positioning Probe Triggers OVC / Scar Commands Initialize Preconditions Measure Start Measurement Stop Measurement DRO Stream X = 2524.4225209935 Milimeter	Algoment TrackerErrors	0.1806 m Active StayOnTop Coordinate	AT500 7 at500si	— [ 1005555 nulator	- ×	
Sharp Sample Project ext Main Profiles Positioning Probe Triggers OVC / Scar Commands Initialize Preconditions Measure Start Measurement Stop Measurement DRO Stream X = 2524 4225209935 Milimeter Y = 1620.8843800571 Milimeter	Inning Algoment TrackerEnors  AT500 Simulator 1.9.  DRO Noise DRO Stream DRO Inclination Sensor Meteo	0.1806 n Active StayOnTop Coordinate X	AT500 7 at500si	– [ 1005555 nulator	- ×	
Sharp Sample Project ext Main Profiles Positioning Probe Triggers OVC / Scar Commands Initialize Preconditions Measurement Start Measurement Stop Measurement DRO Stream X = 2524 42252039355 Milimeter Y = 1620.8843800571 Milimeter Z = 2.3871589805009 Milimeter Taget	Inning Alignment TrackerEnors  AT500 Simulator 1.9  DRO Noise DRO Stream DRO Inclination Sensor Meteo Power Source	0.1806 m Active StayOnTop Coordinate X Y	AT500 7 at500sid 2524.41215401271 1620.90640366644	– [ 1005555 nulator mm	- ×	
Sharp Sample Project          ect       Main       Profiles       Positioning       Probe Triggers       OVC / Scar         Commands       Preconditions       Initialize       Initialize       Initialize       Initialize         Measure       Start Measurement       Stop Measurement       Initialize       Initialize       Initialize         Stop Measurement       Stop Measurement       Initialize       Initialize       Initialize       Initialize         DRO Stream       X       2 5224 42252309395 Millimeter       Y       1620.8843800571 Millimeter         Z       2 3871583850609 Millimeter       Z       2 3871583850609 Millimeter         Target       Selected Target       RRR 1.5in	Inning Alignment TrackerEnors  At500 Simulator 1.9.  DRO Noise DRO Stream DRO Inclination Sensor Meteo Power Source Simulator Timings	0.1806 m Active StayOnTop Coordinate X Y Z	AT500 7 at500sis 2524.41215401271 1620.90640366644 2.38898013219979	– E	- ×	
Sharp Sample Project ect Main Profiles Positioning Probe Triggers OVC / Scar Commands Initialize Preconditions Measure Start Measurement Stop Measurement DRO Stream X = 2524.42252309355 Milimeter Y = 1620.8843800571 Milimeter Z = 2.3871589850609 Milimeter Target Selected Target RRR 1.Sn Measurement Results	Inning Algoment TrackerErrors  AT500 Simulator 1.9.  DRO Noise DRO Stream DRO Inclination Sensor Meteo Power Source Simulator Timings Status Targets Persistency	0.1806 n Active StayOnTop Coordinate X Y Z	AT500 7 at500si 2524.41215401271 1620.90640366644 2.38898013219979 Refresh Units	– [ 1005555 nulator mm mm Apply	- ×	
Sharp Sample Project ect Main Profiles Positioning Probe Triggers OVC / Scar Commands Initialize Preconditions Measure Start Measurement Stop Measurement DRO Stream X = 2524 42252309335 Millimeter Y = 1620.8843800571 Millimeter Z = 2.3871589850609 Millimeter Target Selected Target RRR 1.5in Measurement Results	Inning Algoment TrackerErors  AT500 Simulator 1.9.  DRO Noise DRO Stream DRO Inclination Sensor Meteo Power Source Simulator Timings Status Targets Persistency	0.1806 M Active StayOnTop Coordinate X Y Z	AT500 7 at500si 2524.41215401271 1620.90640366644 2.38898013219979 Refresh Units	– E 1005555 nulator mm Apply	- ×	
Sharp Sample Project ect Main Profiles Positioning Probe Triggers OVC / Scar Commands Initialize Preconditions Measure Start Measurement Stop Measurement DRO Stream X = 2524.42252309935 Millimeter Y = 1620.8843800571 Millimeter Z = 2.3871589850609 Millimeter Target Selected Target RRR 1.5in Measurement Results	Inning Algement TrackerEiron AT500 Simulator 1.9. DRO Noise DRO Stream DRO Inclination Sensor Meteo Power Source Simulator Timings Status Targets Persistency	0.1806 n Active StayOnTop Coordinate X Y Z	AT500 7 at500sin 2524.41215401271 1620.90640366644 2.38898013219979 Refresh Units	– [ 1005555 mulator mm Apply	- X	
Sharp Sample Project eet Main Profiles Positioning Probe Triggers OVC / Scar Commands Initialize Measure Start Measurement Stop Measurement DRO Stream X = 2524.42252309355 Milimeter Y = 1620.8843800571 Milimeter Z = 2.3871589850609 Milimeter Target Selected Target RRR 1.5in Measurement Results	Inning Algement TrackerEirons  Algement TrackerEirons  AT500 Simulator 1.9.  DRO Noise DRO Stream DRO Inclination Sensor Meteo Power Source Simulator Timings Status Targets Persistency	0.1806 n Active StayOnTop Coordinate X Y Z	AT500 7 at500sin 2524.41215401271 1620.90640366644 2.38898013219979 Refresh Units	– [ 1005555 nulator mm mm Apply		
Sharp Sample Project eet Main Profiles Postioning Probe Triggers OVC / Scar Commands  Initialize Preconditions  Measure Start Measurement Stop Measurement DRO Stream X = 2524.4225209935 Milimeter Y = 1620.8843800571 Milimeter Z = 2.3871589850609 Milimeter Target Selected Target RRR 1.5n Measurement Results	nning Algnment TrackerEirons           Image: AT500 Simulator 1.9.           DRO Noise         DRO Stream           DRO         Inclination Sensor           Meteo         Power Source           Simulator Timings         Status           Targets         Persistency	0.1806 n Active StayOnTop Coordinate X Y Z	AT500 7 at500sid 2524.41215401271 1620.90640366644 2.38898013219979 Refresh Units	- [ 1005555 mulator mm mm Apply		
Sharp Sample Project eet Main Profiles Postioning Probe Triggers OVC / Scar Commands Initialize Preconditions Measure Start Measurement Stop Measurement DRO Stream X = 2524,42252309355 Millimeter Y = 1620.8843800571 Millimeter Z = 2.3871589850609 Millimeter Target Selected Target RRR 1.5n Measurement Results	nning Algnment TrackerErions  At500 Simulator 1.9.  DRO Noise DRO Stream DRO Inclination Sensor Meteo Power Source Simulator Timings Status Targets Persistency	0.1806 m Active StayOnTop Coordinate X Y Z	AT500 7 at500sid 2524.41215401271 1620.90640366644 2.38898013219979 Refresh Units	– [ 1005555 nulator mm mm Apply		
Sharp Sample Project eet Main Profiles Postioning Probe Triggers OVC / Scar Commands  Measure Stat Measurement Stop Measurement DRO Stream X = 2524,42252309355 Millmeter Y = 1620.8843800571 Millmeter Z = 2.3871589850609 Millmeter Target Selected Target RRR 1.5n Measurement Results	Inning Algoment TrackerErrors AT500 Simulator 1.9. DRO Noise DRO Stream DRO Inclination Sensor Meteo Power Source Simulator Timings Status Targets Persistency	0.1806 m Active StayOnTop Coordinate X Y Z	AT500 7 at500sid 2524.41215401271 1620.90640366644 2.38898013219979 Refresh Units	– [ 1005555 nulator mm Mm Mm		

Besides the C# SampleProject the COMSampleProject as well as PythonSampleProject can be used.



#### Extended LMF Tracker User guide

The LMF Tracker User guide is updated with the latest changes.

#### Relocation of the battery state to Sensor Power Status

AT500 contains two sensor batteries. Unlike the ATS600 and AT9x0, the battery status and level are represented under SensorPowerStatus, as the batteries are attached to the ATS500 Sensor and not to a controller like in ATS600/AT9x0.

TS TrackerScope  $\times$ at500simulator 🖬 🔩 Face LMF.Tracker.Face 🗄 🔩 InclinationSenso MF.Tracker.Inclination.Inclination • 😂 Laser LMF.Tracker.Laser 🖪 🔩 Measurement LMF.Tracker.Measurements.MeasurementSettings 🖪 🔩 MeteoStation 🖪 🔩 OverviewCamera LMF.Tracker.OVC.OverviewCamero • PowerLock LMF.Tracker.PowerLock PowerSource LMF.Tracker.PowerSource ControllerPowerStatus NULL 🔳 🔩 SensorPowerStatus LMF.Tracker.PowerStatus 🗖 ⅍ Level 🔏 Label Level 🔏 UnitString 🔏 UnitType Percent 🔏 Value 78 ValueInBaseUnits 0.78 Changed 🗖 🔩 RunsOn LMF.Tracker.BasicTypes.EnumTypes.ReadOnlyPowerSourceValue A Label Runs on Battery Changed Changed QuickRelease NULL 🖪 🔩 Settings MF.Tracker.Settings 🕏 Targets LMF.Tracker.Targets.TargetCollection 💱 TargetSearch LMF.Tracker.Targets.Ta

The structure remains the same, the enums have not been extended.

Due to mechanical constraints, it is not possible to measure with one inserted battery only. If this occurs, the user will be informed with the following warning:

InformationArrived	InformationArrived	
🗲 WarningArrived	WarningArrived	
	Parameters	
	🗖 🔩 warning	LMF.Tracker.ErrorHandling.LmfWarning
	hescription 🖌	There is only one battery in the sensor.
	🔏 Number	200127
	Solution 🆌	To be able to measure, please put both batteries into the sensor battery compartments. Both batteries need to have a minimal battery level of at least one percent each.
	🄏 Title	Sensor Battery missing



Besides the two internal batteries it is also possible to connect the AT500 to either the external battery pack (MPB100 / MPB25) or to mains. Therefore LMF 1.9 for AT500 is extended by a third power source item in the AT500 simulator.

TS AT500 Simulator 1.9.0.17	71	_	×
	AT500 71005555 at500simulator		
DRO Noise DRO Stream A	tive StayOnTop		22480
DRO Inclination Sensor	Sensor Power Source		
Meteo Power Source	Battery Temperature		Ŧ
Simulator Timings Status	Second Sensor Power Source		
Targets Persistency	Battery Temperature		-
	Third Sensor Power Source		
	Mains		

The overall battery level is calculated as follows

Battery level = Max (min (int1, Int2), Ext3)

Where

```
Int1 = Internal battery 1
Int2 = Internal battery 2
Ext3 = External battery 3
```

Hence, only one battery level will be provided through the interface, as for AT40x, AT9x0 and ATS600.

#### Battery temperature warnings and errors

The ATS500 sensor batteries itself might throw warnings or errors on a real device. They appear as usual in the warnings or error handler.

Those warnings/errors can be simulated as follows:



TS AT500 Simulator 1.9.0.17	771	-		×	
	AT500 AT500	71005555 Simulator		22490	
DRO Noise DRO Stream A DRO Inclination Sensor	Sensor Power Source			22480	
Meteo Power Source	Battery 100 %	Temperature Ok		-	
Simulator Timings Status	Second Sensor Power Source	Tomporatura			
Persistency	Battery 100 %	Warning	1		
	Third Sensor Power Source	OK Warning Critical			
	L	Overtemperature			

The "Warning" status will return the following warning:

🗲 InformationArrived	InformationArrived	InformationArrived				
🗲 WarningArrived	WarningArrived	WarningArrived				
	Parameters					
	🗖 🔧 warning	LMF.Tracker.ErrorHandling.LmfWarning				
	hescription 🖌	A Description Battery temperature is high.				
	🔏 Number	200125				
	🔏 Solution	Consider connecting AC power.				
	🔏 Title	Battery temperature high				

As soon as the battery reaches a "Critical" temperature, the user is informed to change the battery immediately or connect the tracker to mains.

InformationArrived	InformationArrived	
🗲 WarningArrived	WarningArrived	
	Parameters	
	🗖 🔩 warning	LMF.Tracker.ErrorHandling.LmfWarning
	🔏 Description	System temperature is too high for battery operation.
	🔏 Number	200126
	🔏 Solution	Stop battery operation immediately by connecting AC power.
	🔏 Title	Battery temperature critical

In this case the sensor drives are turned off; the user is not able to measure anymore.



If the battery reaches an overtemperature a tracker shut down will be triggered.

#### Bubble read out stream for accurate levelling

AT500 is the first Leica Absolute Tracker which is integrating the controller in the sensor head itself. As a result, the user is not able to see information related to accurate levelling on the controller display anymore; a major difference compared to AT9x0 and ATS600. To provide the minimal information needed regarding the accurate levelling of an AT500, LMF 1.9 is extended by a subtree called "BubbleReadout" within InclinationSensor.

_	
TS TrackerScope	– 🗆 X
-	at500simulator
🔏 IsCompatibleWithInstalledFirmware	
🔏 Name	AT500 71005555
🔏 ProductName	AT500
🔏 SerialNumber	71005555
🖪 🔩 Compensations 🍡 🏉	LMF.Tracker.Compensations.CompensationCollection
🖬 🔩 Face	LMF.Tracker.Face
🗖 🔩 InclinationSensor	LMF.Tracker.Inclination.InclinationSensor
🗖 🔩 BubbleReadout 📕	LMF.Tracker.Inclination.InclinationBubbleReadout
😚 StartBubbleReadoutStream	StartBubbleReadoutStream
😚 StopBubbleReadoutStream	StopBubbleReadoutStream
🗲 BubbleReadoutArrived	BubbleReadoutArrived
🔩 CurrentInclinationToGravity	NULL
🖪 🔩 InclinedToGravity	LMF.Tracker.BasicTypes.BoolValue.BoolValue
🖪 🔩 Monitoring	LMF.Tracker.Inclination.InclinationMonitoring
🛇 GetInclinationToGravity	GetInclinationToGravity
😚 GetInclinationToGravityAsync	GetInclinationToGravityAsync
😚 Measure	Measure
🗲 GetInclinationToGravityFinished	GetInclinationToGravityFinished
🖪 🔩 Laser	LMF.Tracker.Laser
🖪 🔩 Measurement	LMF.Tracker.Measurements.MeasurementSettings
MeteoStation	LMF.Tracker.Meteo.MeteoStation
🖪 🔩 OverviewCamera	LMF.Tracker.OVC.OverviewCamera
PowerLock	LMF.Tracker.PowerLock
🗖 🔩 PowerSource	LMF.Tracker.PowerSource
🔩 ControllerPowerStatus	NULL

Below this new subtree all related calls and events receivers are grouped.

- InclinationSensor->BubbleReadout->StartBubbleReadoutStream
- InclinationSensor->BubbleReadout->StopBubbleReadoutStream
- InclinationSensor->BubbleReadout->BubbleReadoutArrived

The COMSampleProject contains the InclinationStreamData.



Additionally, AT500 will be released with a mobile application which provides the leveling and changing the network settings as known from the AT9x0 and ATS600 controller.

#### Optional (Bluetooth) object temperature sensor

AT500 will be released with a Bluetooth module which enables the possibility to connect the AT500 sensor with a Bluetooth temperature sensor.

The LMF structure has however not changed, the structure and behavior are the same as with an Object Temperature Sensor on any other Leica Tracker.

<sup>15</sup> TrackerScope		-	- 🗆 🗙		
	AT500Simulator	•	- 🚺		
HardwareHumidity	LMF.Tracker.Meteo.EnvironmentalSensor			-	
🖪 🔩 HardwarePressure	LMF.Tracker.Meteo.EnvironmentalSensor				
HardwareTemperature	LMF.Tracker.Meteo.EnvironmentalSensor				
IsAirSensorConnected	LMF.Tracker.BasicTypes.BoolValue.ReadOnlyBoolValue				
🖪 🔩 ManualHumidity	LMF.Tracker.Meteo.ManualEnvironmentalSensor				
ManualPressure	LMF.Tracker.Meteo.ManualEnvironmentalSensor	_			
🖪 🔩 ManualTemperature	LMF.Tracker.Meteo.ManualEnvironmentalSensor	AT500 Simulator 1.9.0.1	806		- 🗆 ×
ObjectTemperature	LMF.Tracker.Meteo.EnvironmentalSensor			AT500 71005555	
🔏 Label	Temperature			AT500Simulator	
🔏 SerialNumber	234-6542-9876			ATOUSIIIIulator	
🔏 UnitString	°C	DRO Noise DRO Stream A	Active StayOnTop		224
🔏 UnitType	Temperature	DRO	Contract Mater		
🔏 Value	23	Inclination Sensor	Internal Meteo		
🔏 ValueInBaseUnits	23	Meteo	Defect		
🖪 🔩 Available	LMF.Tracker.BasicTypes.BoolValue.ReadOnlyBoolValue	Power Source	Temperature		20 [°C]
🗲 Changed	Changed	Simulator Timings			
	Parameters	Status	Humiditiy		60 [%]
🖪 🔩 Source	LMF.Tracker.Meteo.MeteoSource	Targets	Pressure		1013 [mBar]
EnvironmentalValuesChanged	EnvironmentalValuesChanged	Persistency	Object Terrarety		
🖪 🔩 OverviewCamera	LMF.Tracker.OVC.OverviewCamera	/	Object Temperatur	re Sensor	
PowerLock	LMF.Tracker.PowerLock	/	Connected	<i>p</i>	
🖪 🔩 PowerSource	LMF.Tracker.PowerSource	1 1	Temperature		23 [°C]
⁴\$ QuickRelease	NULL	1 1			
🖪 🔩 Settings	LMF.Tracker.Settings	1 1	External Temperate	ure Sensor	
Targets	LMF.Tracker.Targets.TargetCollection	1 1			
n 🕂 TargetSearch	I ME Trackar Taraats TaraatSaarch	4 /	Plugged in		
	1	/	Temperature		20 [°C]
		4 ,			

The received temperature value is shown as the ObjectTemperature.



#### No quick release detection

In contrast to AT9x0 and ATS600, the quick release detection is not supported for AT500.

<sup>15</sup> TrackerScope	- 🗆 X	
	AT500Simulator	
AT500Simulator	LMF.Tracker.AT500Tracker	
🔏 Comment	Simulator	
🔏 ExpectedFirmware	1.0.0.0	
🔏 InstalledFirmware	1.0.0.0	
🔏 IPAddress	AT500Simulator	
🔏 IsCompatibleWithInstalledFirmware		
🔏 Name	AT500 71005555	
🔏 ProductName	AT500	
🔏 SerialNumber	71005555	
🖪 🔩 Compensations	LMF.Tracker.Compensations.CompensationCollection	
🖪 🔧 Face	LMF.Tracker.Face	
InclinationSensor	LMF.Tracker.Inclination.InclinationSensor	
🖪 🔩 Laser	LMF.Tracker.Laser	
🖪 🔩 Measurement	LMF.Tracker.Measurements.MeasurementSettings	
🖪 🔩 MeteoStation	LMF.Tracker.Meteo.MeteoStation	
🖪 🔩 OverviewCamera 💦 👝	LMF.Tracker.OVC.OverviewCamera	
🗈 🔩 PowerLock	LMF.Tracker.PowerLock	
🖻 🔩 PowerSource	LMF.Tracker.PowerSource	
🔩 QuickRelease	NULL	
🖪 🔩 Settings	LMF.Tracker.Settings	
🖪 🔩 Targets	LMF.Tracker.Targets.TargetCollection	
🖪 🔩 TargetSearch	LMF.Tracker.Targets.TargetSearch	
🖪 🔩 TrackerAlignment	LMF.Tracker.TrackerAlignments.TrackerAlignment	
🖪 🔩 Triggers	LMF.Tracker.Triggers.TriggerCollection	
🕎 Disconnect	Disconnect	
😚 Dispose	Dispose	
Congratal File	Constant Sile	

## Support for the new B-Probe<sup>plus</sup>

LMF 1.9 introduces a new B-Probe class called "BProbePlus" which is provided with an AT500 only.

The known B-Probe class remains for AT40x.

The reason to introduce a new class for the B-Probe <sup>plus</sup> on an ATS500 is the fact that this device behaves significantly different to a B-Probe on an AT40x. The main differences are detailed below.

- 6Dof DRO with
  - Shank directions/6dof rotation
  - o Positions related to ball center

This feature e.g., allows inspecting a part by moving the probe over the part and comparing DRO to CAD, same as a T-Probe on an AT9x0. This is not possible with a B-Probe for AT40x as here the DRO only refers to the probe reflector and cannot be used for such workflows.



Secondly, the B-Probe <sup>plus</sup> will not generate measurements when the user releases the button on the device, as it is currently done for the B-Probe on an AT40x. Instead, the user receives a button event if the measurement button on the B-Probe plus is pressed manually. For the B-Probe plus the button-up is changed to a button-down event. By means of the button down event the 3<sup>rd</sup> party software can react correspondingly, e.g. by invoking a measurement with *startMeasurement*.

			TS AT500 Simulator 1.9.	0.2090	-	
					AT500 71005555 AT500Simulator	
TS TrackerScope			DRO Noise DRO Stream	n Active StayOnTop		22480
-	AT500S	imulator	DRO Inclination Sensor	Sensor pointing to		
🖪 🔩 Targets	LMF.Tracker.Targets.Target	Collection	Power Source	Target BP	obe plus 👻	
🖪 🔩 TargetSearch	LMF.Tracker.Targets.TargetS	Search	Simulator Timings	Target Action		
🖪 🔩 TrackerAlignment	LMF.Tracker.TrackerAlignme	ents.TrackerAlignment	Status			
🗖 🔩 Triggers	LMF.Tracker.Triggers.Trigge	rCollection	Targets		<u></u>	
🖪 🔩 [0] StableProbingTrigger	LMF.Tracker.Triggers.Stable	ProbingTrigger	Persistency		в	
🗖 🔩 [1] BProbeButtonTrigger	LMF.Tracker.Triggers.BProbe	ButtonTrigger		Probe Recognized	Stable Probing B-Probe plus Button	
🔏 GUID	cca4a593-13f7-4f28-af1a-c	10a874cede7		Those necognized		
🔏 Name	B-Probe Button					
🖪 🔩 IsEnabled	LMF.Tracker.BasicTypes.Boo	lValue.BoolValue				
🛇 RaiseButtonPressed		RaiseButtonPressed				
🔏 Count	2					
🗲 TriggerHappened	TriggerHappened					
	Parameters					
	🗖 🔩 paramTrigger	LMF.Tracker.Triggers.BProbeB	uttonTrigger			
	🔏 GUID	cca4a593-13f7-4f28-af1a-c10	a874cede7			
	🔏 Name	B-Probe Button				
	🗖 🔩 IsEnabled	LMF.Tracker.BasicTypes.BoolV	alue.BoolValue			
	🔏 Label	Is enabled				
	🔑 Value					
	🗲 Changed	Changed				
	RaiseButtonPres	Raiset	ButtonPressed			
🛇 Disconnect		Disconnect				
🛇 Dispose	Dispose					
🛇 GenerateLFile		GenerateLFile				
😚 GetDirection		GetDirection				
GetDirectionAsvnc		GetDirectionAsync				

Similarities from B-Probe plus to B-Probe

- B-Probe <sup>plus</sup> needs to be selected manually, there is no automatic recognition by the sensor. Consequently, there will be no unsolicited selected target changed event triggered by the sensor (as it can be the case on a T-Probe), the selected target only changes when the user selects it.
- Measurement structures delivered by a B-Probe <sup>plus</sup> are the same as the ones delivered by a B-Probe on an AT40x.



• The B-Probe <sup>plus</sup> does not allow continuous time or continuous distance measurements. Therefore, the same restrictions as for the B-Probe regarding the measurement modes also apply for the B-Probe plus.

				TS AT500 Simulator 1.9.0.	2090	-	
						AT500 71005555 AT500Simulator	
TS TrackerScope				DRO Noise DRO Stream	Active StayOnTop		2248
Profiles	AT500Simulator		DRO Inclination Sensor Meteo	Sensor pointing Target	to BProbe plus		
🖪 🔩 [0] StationaryMeasure	LMF.Tracker.Measurements.	Profiles.Stationary	Measurement	Simulator Timings	Target Action		
🖪 ⅍ [1] ContinuousTimePr	LMF.Tracker.Measurements.	Profiles.Continuou	IsTimeProfile	Status			
🔳 🔩 [2] ContinuousDistan	LMF.Tracker.Measurements.	Profiles.Continuou	sDistanceProfi	Targets			
🔏 GUID	41a3c1a9-a17b-4f59-8953-	41a3c1a9-a17b-4f59-8953-608f795ce6ce		Persistency		в	
🔏 Name	Continuous Distance				Probe Recogni	zed Stable Probing B-Probe plus Button	
🖪 🔩 DistanceSeparatic	LMF.Tracker.BasicTypes.Dou	ibleValue.De Excep	tion		×	5	
🕎 Select		#200	050 Exception				
🔏 Count	3	#200	058 Exception		_		
🗖 🔩 Selected 📐	LMF.Tracker.Measurements.	Profiles.Con	Error# 200	058			
🔏 GUID	41a3c1a9-a17b-4f59-8953-608f795ce6 Continuous Distance		Continuou	is Measurement not possible			
🔏 Name 🦰 🐂			Continuou	Measurements are not			
🖪 🔩 DistanceSeparatic	LMF.Tracker.BasicTypes.Dou	bleValue.Do	Select a R	eflector to do Continuous			
😚 Select			Measurem	ients or change the			
🗲 SelectedChanged	SelectedChanged		Measurem measure v	entProfile to Stationary to vith a B-Probe			
	Parameters				_		
🖬 🔩 Status	LMF.Tracker.MeasurementSt	tatus.Measuremen	tStatusValue				
🛇 GoAndMeasureStationary	Parameter						
	GoAndMeasureStationary						
GoAndMeasureStationaryAs	Parameter						
· · · · · · · · · · · · · · · · · · ·		GoAndMeasu	reStationaryAsyn	c			
MeasureStationary	MeasureStationary						
	ReturnValue     LMF. Tracker. MeasurementResult		ts.StationarvMeasurement	6D			
StartMeasurement	-	StartMo	easurement				
StopMeasurement	StopMeasurement						
MeasurementArrived	MeasurementArrived						

• There is no shank compensation available for a B-Probe <sup>plus</sup>. Shank measurements are still not supported by the B-Probe <sup>plus</sup>; same as for the B-Probe.

The newly introduced B-Probe plus can be found under



	AT500Simulator		
\$ Targets	LMF.Tracker.Targets.TargetCollection		
🛢 🔩 [0] ToolingBallReflector05	LMF.Tracker.Targets.Reflectors.ToolingBallReflector05		
1 1 FixedInstallationReflector0	5 LMF.Tracker.Targets.Reflectors.FixedInstallationReflector05		
🛿 🔩 [2] RedRingReflector05	LMF.Tracker.Targets.Reflectors.RedRingReflector05		
3 1 (3) BreakResistantReflector15	LMF.Tracker.Targets.Reflectors.BreakResistantReflector15		
🛿 🔩 [4] RedRingReflector15	LMF.Tracker.Targets.Reflectors.RedRingReflector15		
🛿 🔩 [5] MirrorReflector	LMF.Tracker.Targets.Reflectors.MirrorReflector		
1 1 (6) RedRingReflector78	LMF.Tracker.Targets.Reflectors.RedRingReflector78		
🛿 🔧 [7] CustomReflector	LMF.Tracker.Targets.Reflectors.CustomReflector		
🛿 🔩 [8] CustomReflector	LMF.Tracker.Targets.Reflectors.CustomReflector		
🛿 🔩 [9] BProbePlus 🛛 📕	LMF.Tracker.Targets.Probes.PassiveProbes.BProbes.BProbePlus		
🔏 Comment			
🔏 GUID	3439954f-bd9e-420d-8d2a-16f47e4c2637		
🔏 IsSelectable			
🔏 Name	#0112 (12.7 mm)		
🔏 ProductName	B-Probe plus		
🔏 SerialNumber	0112		
🔏 TimeStamp	Wednesday, 23. October 2013 12:00:00.000		
🖪 🔩 FaceCompensation	LMF.Tracker.Targets.Probes.PassiveProbes.BProbes.BProbeFaceCompensation		
🖪 🔩 TipCompensation	LMF.Tracker.Targets.Probes.PassiveProbes.BProbes.BProbeTipCompensation		
😚 Deselect	Deselect		
😚 GetLockOnToken	GetLockOnToken		
😚 Select	Select		
🖌 Count	10		
🛯 🔩 PreSelected	LMF.Tracker.Targets.Reflectors.RedRingReflector15		
🛯 🔧 Selected	LMF.Tracker.Targets.Reflectors.RedRingReflector15		

TS AT500 Simulator 1.9.0.1	848		_	×
		AT500 71005555		
		AT500Simulator		
DRO Noise DRO Stream A	ctive StayOnTop			22480
DRO Inclination Sensor	Sensor pointing	; to		
Meteo	Target	BProbe plus	-	
Simulator Timings	Target Action	Reflector No Target		
Targets Persistency		BProbe plus		
	Probe Recogni	ized Stable Probing B-Probe Butto	n	



## General improvements

#### Allocation of the bubble read out stream

This feature introduced in LMF 1.9 for the AT500 is also available for the ATS600 and the AT9x0. For ATS600 and AT9x0 the user has now the option to perform an accurate levelling, either by using the screen on the controller or by using the bubble read-out stream provided by LMF.

## Improvements for the AT9x0 interface

LMF 1.9 contains a specific fix for the AT9x0 interface which solves a connection/disconnection issue caused by an internal race condition. In rare cases the initial connection to an AS1 does not start the RDS interface after a beam break since LMF has not been properly disconnect before. Hence, a re-connection could not be established. Latter issue is fixed in LMF 1.9.

## Improvements for the ATS600 interface

LMF 1.9 includes an improvement for the ATS600 interface: as part of the area scan the minimum distance for programmatically added boundary points is shortened from 1.5m to 1m. The option to enter corresponding perimeter directly in the OVC was possible prior to LMF 1.9, latter minimum distance is now also available for programmatically added points.





## Improvements for the AT40x interface

LMF 1.9 contains a bug fix for the AT40x interface, which allows the user to invoke StartMeasurement multiple times when the OutdoorProfile is selected. The fix sets the MeasurementInProgress flag to false after the measurement is finished.

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